

Computing Architectures and Algorithms

Sparse Matrices

#### What are sparse matrices?

- Matrices with large number of zero entries
- If there are enough zeros, it might be worth using an algorithm that avoids:
  - o Storing zero entries
  - o Operating on zero entries

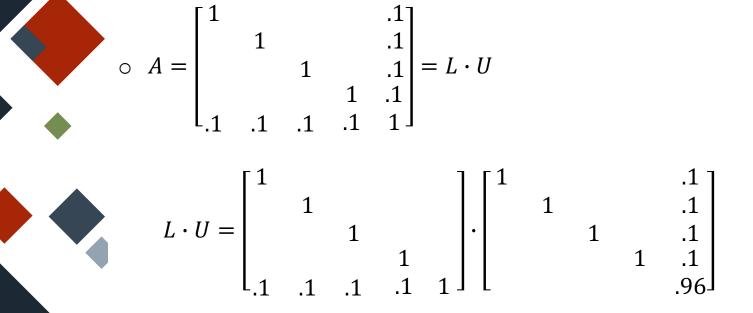
# How should our algorithm deal with sparse matrices?

- Many sparse methods available
- Choosing the best one often requires substantial knowledge about the matrix
- We shall focus on basic issues in sparse Gaussian elimination
- Supplementary references and exercises you can try on MATLAB are provided

Examples of Sparse Matrices and Issues to Consider

An arrow matrix forms an arrow with its nonzero entries
Consider the example below:

[The zero entries have been left blank]
What happens when we perform LU factorization? (try to solve it yourself manually—or use software)



- None of the zero entries of A were filled in
- L and U together can be stored in (overwrite) the nonzero entries of A
- Total *essential* arithmetic operations (exclude adding or multiplying by zero): only 12
  - o 4 divisions for last row of L
  - 8 multiplications and additions to compute the bottom rightmost entry (0.96 in the example)

- LU factorization on a typical (not sparse) n-by-n matrix:
   Need n<sup>2</sup> locations to store matrix
  - $\circ \frac{2}{3}n^3$  floating point operations
- LU factorization on an n-by-n arrow matrix:
  - Only need 3n 2 locations to store matrix
  - $\circ$  3n 3 floating point operations
- When n is large, space required and number of operations is tiny compared to dense LU factorization

# What if we reversed the order of columns and rows?

 Suppose we instead had A' shown below. What happens when we do LU factorization?

$$A' = \begin{bmatrix} 1 & .1 & .1 & .1 & .1 \\ .1 & 1 & & & \\ .1 & 1 & & & \\ .1 & & & 1 & \\ .1 & & & & 1 \end{bmatrix}$$

### L' and U' have filled completely!

1

1

1

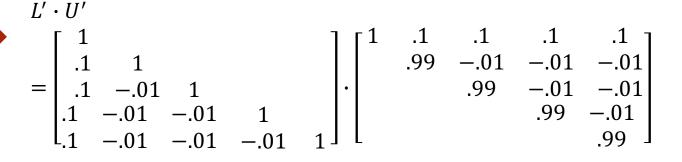
- 1

L'

$$A' = \begin{bmatrix} 1 & .1 & .1 & .1 & .1 \\ .1 & 1 & & \\ .1 & 1 & & \\ .1 & & 1 & \\ .1 & & & 1 \end{bmatrix} = L' \cdot U'$$
$$\cdot U' = \begin{bmatrix} 1 & .1 & .1 & .1 & .1 & .1 \\ .1 & .01 & .01 & 1 \\ .1 & .01 & -.01 & 1 \\ .1 & .01 & -.01 & .1 \end{bmatrix} \cdot \begin{bmatrix} 1 & .1 & .1 & .1 & .1 & .1 \\ .99 & -.01 & .01 & .01 \\ .99 & -.01 & .01 \\ .99 & -.01 \\ .99 & -.01 \\ .99 & -.01 \end{bmatrix}$$

1 -

# Need to use dense Gaussian elimination



• Need  $n^2$  locations to store L' and U'

Same amount of work as dense Gaussian elimination,  $\frac{2}{3}n^3$ 

# Order of rows and columns is extremely important!

# How do we choose optimal permutations of rows and columns?

- We have seen that we can minimize storage if the correct order of rows/columns is used
- However, choosing the optimal order or permutations of rows and columns is extremely hard (NP-complete!)
  - $\circ\,$  All known algorithms to find optimal permutation grows exponentially with  $n\,$
  - We need to settle for using heuristics (more practical/experimental way of problem-solving, but may not be most optimal)

### Rough strategy for optimizing Factorization of Sparse Matrices

- 1. Design/choose a data structure that holds only nonzero entries of A
- 2. Design/choose data structure to accommodate new entries of L and U that fill in during elimination
  - Option 1: Data grows dynamically
  - Option 2: Pre-compute size w/o actually performing elimination (computation must not be costly)
- 3. Use the data structure to perform only minimum number of floating point operations

### Learn by Benchmarking!

- Check out this MATLAB example: <u>https://www.mathworks.com/help/matlab/math/sparse-</u> <u>matrix-reordering.html</u>
- Follow the discussion and try to run the sample codes on MATLAB Online (your up.edu.ph webmail account should have access)

View MATLAB Command

 If you need a tutorial on Cholesky decomposition, see the youtube link provided on UVLe

### **Software for Sparse Matrix Operations**

#### • MATLAB:

- Operations on sparse matrices return sparse matrices; operations on full matrices return full matrices
   MATLAB only stores nonzero entries of sparse matrices
- Has built in functions for sparse matrix creation and manipulation

spalloc	Allocate space for sparse matrix	
spdiags	Extract nonzero diagonals and create sparse band and diagonal matric	
speye	Sparse identity matrix	
sprand	Sparse uniformly distributed random matrix	
sprandn	Sparse normally distributed random matrix	
sprandsym	Sparse symmetric random matrix	
sparse	Create sparse matrix	

https://www.mathworks.com/help/matlab/sparse-matrices.html

### **Software for Sparse Matrix Operations**

- Other public domain and commercial sparse matrix software are available
- Active research area; difficult to recommend a single best algorithm

#### **Software for Sparse Matrix Operations**

			<u> </u>	
Matrix			Status/	
type	Name	Algorithm	source	
Serial algo	orithms			
nonsym.	SuperLU	LL, partial, BLAS-2.5	Pub/NETLIB	
nonsym.	UMFPACK [62, 63]	MF, Markowitz, BLAS-3	Pub/NETLIB	
	MA38 (same as UMFPACK)	)	Com/HSL	
nonsym.	MA48 [96]	Anal: RL, Markowitz	Com/HSL	
		Fact: LL, partial, BLAS-1, SD		
nonsym.	SPARSE [167]	RL, Markowitz, scalar	Pub/NETLIB	Abbreviations used in the table:
sym- )	∫ MUPS [5]	MF, threshold, BLAS-3	Com/HSL	nonsym. = nonsymmetric.
pattern ∫	[ MA42 [98]	Frontal, BLAS-3	Com/HSL	sym-pattern = symmetric nonzero structure, nonsymmetric values
sym.	MA27 [97]/MA47 [95]	MF, $LDL^T$ , BLAS-1/BLAS-3	Com/HSL	sym. $=$ symmetric and may be indefinite.
s.p.d.	Ng & Peyton [191]	LL, BLAS-3	Pub/Author	s.p.d. $=$ symmetric and may be intermited s.p.d. $=$ symmetric and positive definite.
Shared-me	emory algorithms	•		MF, LL, and $RL$ = multifrontal, left-looking, and right-looking.
nonsym.	SuperLU	LL, partial, BLAS-2.5	Pub/UCB	SD = switches to a dense code on a sufficiently dense trailing sub
nonsym.	PARASPAR [270, 271]	RL, Markowitz, BLAS-1, SD	Res/Author	Pub = publicly available; authors may help use the code.
sym-	MUPS [6]	MF, threshold, BLAS-3	Res/Author	
pattern				Res = published in literature but may not be available from the a
nonsym.	George & Ng [115]	RL, partial, BLAS-1	Res/Author	Com = commercial.
s.p.d.	Gupta et al. [133]	LL, BLAS-3	Com/SGI	HSL = Harwell Subroutine Library:
			Pub/Author	http://www.rl.ac.uk/departments/ccd/numerical/hsl/hsl.
s.p.d.	SPLASH [155]	RL, 2-D block, BLAS-3	Pub/Stanford	UCB = http://www.cs.berkeley.edu/~xiaoye/superlu.html.
Distribute	ed-memory algorithms			Stanford = http://www-flash.stanford.edu/apps/SPLASH/.
sym.	van der Stappen [245]	RL, Markowitz, scalar	Res/Author	
sym-	Lucas et al. [180]	MF, no pivoting, BLAS-1	Res/Author	
pattern	100 0000			
s.p.d.	Rothberg & Schreiber [207]	RL, 2-D block, BLAS-3	Res/Author	
s.p.d.	Gupta & Kumar [132]	MF, 2-D block, BLAS-3	Res/Author	
s.p.d.	CAPSS [143]	MF, full parallel, BLAS-1	Pub/NETLIB	
		(require coordinates)		

Software to solve sparse linear systems, taken from Applied Numerical Linear Algebra by James W. Demmel

### Key Takeaways

- Sparse matrices provide computational advantages:
   Memory management: minimize required memory
  - locations by storing only nonzero elements
  - Computational efficiency: only perform *essential* operations, i.e. do not perform multiplications and additions by 0, for example
- Choosing the best algorithm/software is not straightforward
  - Need substantial knowledge of the matrix to know the optimal data structure and algorithm
  - No "one-size-fits-all" solution